# HEF4020B-Q100

**14-stage binary counter** Rev. 3 — 7 December 2021

### 1. General description

The HEF4020B is a 14-stage binary ripple counter with a clock input ( $\overline{CP}$ ), an overriding asynchronous master reset input (MR) and 12 buffered parallel outputs (Q0, and Q3 to Q13). The counter advances on the HIGH-to-LOW transition of  $\overline{CP}$ . A HIGH on MR clears all counter stages and forces all outputs LOW, independent of the state of  $\overline{CP}$ . Each counter stage is a static toggle flip-flop. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V<sub>DD</sub>.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

### 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)

  Specified from -40 °C to +85 °C
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- High speed operation
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
  - MIL-STD-883, method 3015 exceeds 2000 V
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0 Ω)
- Complies with JEDEC standard JESD 13-B

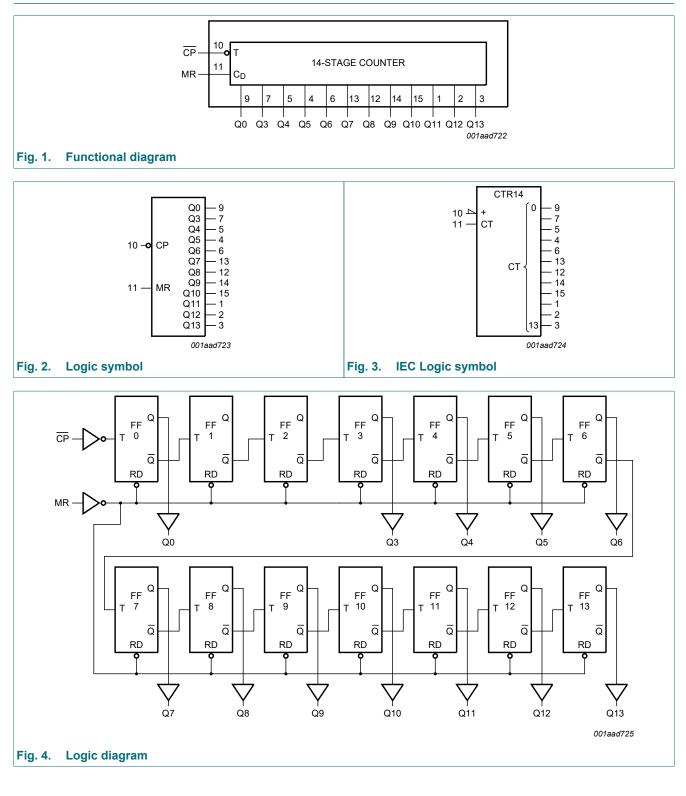
### 3. Ordering information

#### Table 1. Ordering information

Type number	Package					
	Temperature range	Name	Description	Version		
HEF4020BT-Q100	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1		

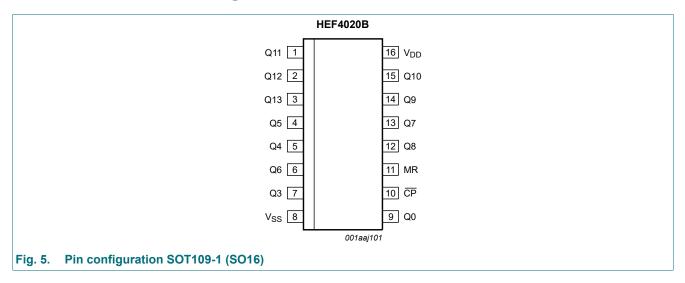


# 4. Functional diagram



### 5. Pinning information

### 5.1. Pinning



### 5.2. Pin description

#### Table 2. Pin description

Symbol	Pin	Description
Q3, Q4, Q5, Q6, Q7, Q8, Q9, Q10, Q11, Q12, Q13	7, 5, 4, 6, 13, 12, 14, 15, 1, 2, 3	parallel output (Q3 to Q13)
V <sub>SS</sub>	8	ground supply voltage
Q0	9	parallel output
CP	10	clock input (HIGH-to-LOW edge triggered)
MR	11	master reset input (active HIGH)
V <sub>DD</sub>	16	supply voltage

### 6. Functional description

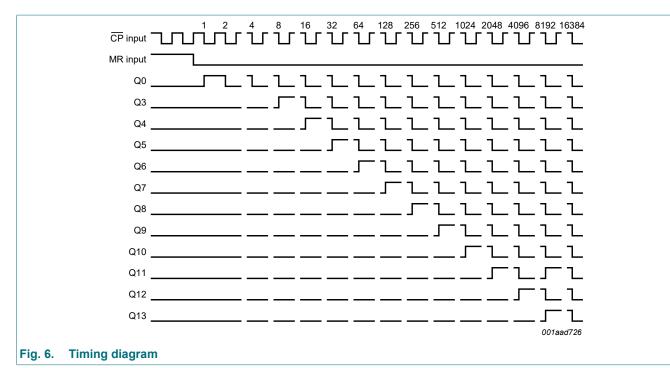
#### Table 3. Functional table

H = HIGH voltage level; L = LOW voltage level; X = don't care;  $\uparrow = positive-going transition; \downarrow = negative-going transition.$ 

Input	Output	
СР	MR	Q0, Q3 to Q13
1	L	no change
$\downarrow$	L	count
X	Н	L

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#### 14-stage binary counter



### 7. Limiting values

#### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{\rm I}$ < -0.5 V or $V_{\rm I}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{\rm O}$ < -0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> -40 °C to +85 °C	-	500	mW
Р	power dissipation	per output	-	100	mW

### 8. Recommended operating conditions

#### Table 5. Recommended operating conditions

Table 5. Recommended operating conditions								
Symbol	Parameter	Conditions	Min	Тур	Мах	Unit		
V <sub>DD</sub>	supply voltage		3	-	15	V		
VI	input voltage		0	-	V <sub>DD</sub>	V		
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C		
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	µs/V		
		V <sub>DD</sub> = 10 V	-	-	0.5	µs/V		
		V <sub>DD</sub> = 15 V	-	-	0.08	µs/V		

# 9. Static characteristics

#### Table 6. Static characteristics

 $V_{SS} = 0 V$ ;  $V_{I} = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	-40 °C	T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> = +85 °C		Unit
				Min	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level input voltage	I <sub>O</sub>   < 1 μΑ	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level input voltage	I <sub>O</sub>   < 1 μΑ	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level output voltage	I <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		V <sub>O</sub> = 0.5 V	10 V	1.3	-	1.1	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
l <sub>l</sub>	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μA
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	20	-	20	-	150	μA
			10 V	-	40	-	40	-	300	μA
			15 V	-	80	-	80	-	600	μA
CI	input capacitance		-	-	-	-	7.5	-	-	pF

# **10.** Dynamic characteristics

#### Table 7. Dynamic characteristics

 $V_{SS} = 0 V$ ;  $T_{amb} = 25 °C$ ; for test circuit see Fig. 8.

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula [1]	Min	Тур	Max	Unit
t <sub>PHL</sub> HIGH to LOW	CP to Q0;	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns	
	propagation delay	see Fig. 7	10 V	34 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	65	ns
		Qn to Qn + 1	5 V	53 ns + (0.55 ns/pF)C <sub>L</sub>	-	80	160	ns
			10 V	19 ns + (0.23 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	12 ns + (0.16 ns/pF)C <sub>L</sub>	-	20	40	ns
		MR to Qn;	5 V	153 ns + (0.55 ns/pF)C <sub>L</sub>	-	180	360	ns
		see Fig. 7	10 V	79 ns + (0.23 ns/pF)C <sub>L</sub>	-	90	180	ns
			15 V	62 ns + (0.16 ns/pF)C <sub>L</sub>	-	70	140	ns
t <sub>PLH</sub> LOW to HIGH	CP to Q0;	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns	
	propagation delay	see <u>Fig. 7</u>	10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	95	ns
		15 V	27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns	
	Qn to Qn + 1	5 V	43 ns + (0.55 ns/pF)C <sub>L</sub>	-	70	140	ns	
			10 V	14 ns + (0.23 ns/pF)C <sub>L</sub>	-	25	50	ns
		15 V	12 ns + (0.16 ns/pF)C <sub>L</sub>	-	20	40	ns	
t <sub>t</sub>	transition time	see <u>Fig. 7</u>	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>W</sub>	pulse width	CP = HIGH;         minimum width;	5 V		50	25	-	ns
			10 V		25	15	-	ns
		see <u>Fig. 7</u>	15 V		20	10	-	ns
		MR = HIGH;	5 V		130	65	-	ns
		minimum width; see <u>Fig. 7</u>	10 V		95	50	-	ns
		see <u>rig. /</u>	15 V		90	45	-	ns
t <sub>rec</sub>	recovery time	MR input;	5 V		115	60	-	ns
		see Fig. 7	10 V		65	35	-	ns
			15 V		55	25	-	ns
f <sub>max</sub>	maximum frequency	see Fig. 7	5 V		5	10	-	MHz
			10 V		13	25	-	MHz
			15 V		18	35	-	MHz

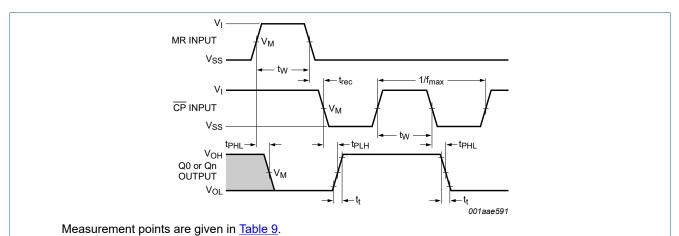
[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

#### Table 8. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0$  V;  $t_r = t_f \le 20$  ns;  $T_{amb} = 25$  °C.

Symbol	Parameter	V <sub>DD</sub>	Typical formula for $P_D$ ( $\mu$ W)	where:
P <sub>D</sub>	dynamic power	5 V	· · · · · · · · · · · · · · · · · · ·	$f_i = input frequency in MHz,$
	dissipation 10 V	10 V	$P_{D} = 2800 \times f_{i} + \sum (f_{o} \times C_{L}) \times V_{DD}^{2}$	$f_o = output frequency in MHz, C_I = output load capacitance in pF,$
	15 V		$P_{D} = 8200 \times f_{i} + \sum (f_{o} \times C_{L}) \times V_{DD}^{2}$	$V_{DD}$ = supply voltage in V, $\Sigma(f_o \times C_L)$ = sum of the outputs.

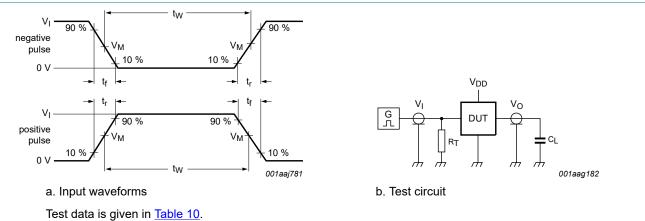
### 10.1. Waveforms and test circuit



#### Fig. 7. Propagation delays, minimum pulse widths, transition and recovery times and maximum clock frequency

#### Table 9. Measurement points

Supply voltage	Input	Output
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



Definitions for test circuit:

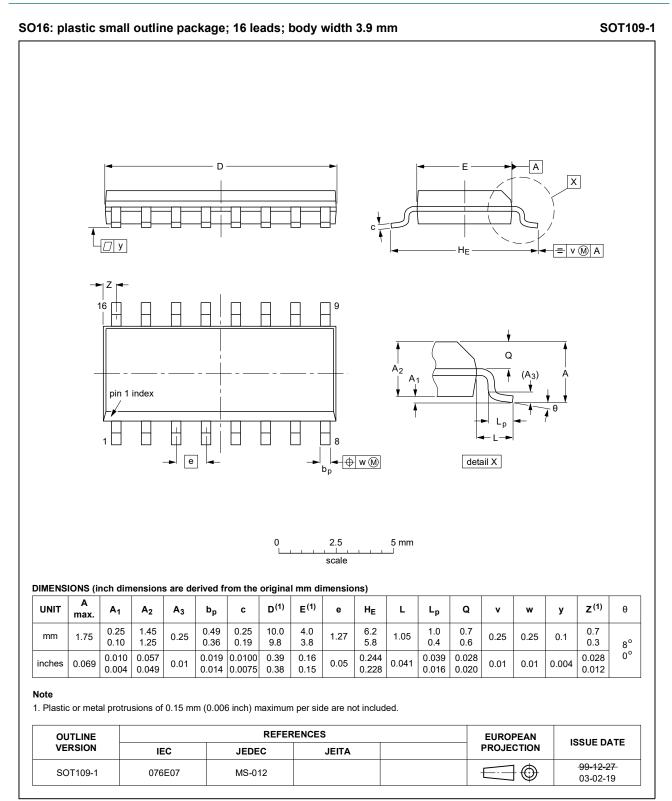
 $C_L$  = load capacitance including jig and probe capacitance.

 $R_T$  = termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator.

#### Fig. 8. Test circuit for measuring switching times

Table 10. Test data							
Supply voltage	Load						
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL				
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF				

### 11. Package outline



#### Fig. 9. Package outline SOT109-1 (SO16)

# 12. Abbreviations

Table 11. Abbreviations				
Acronym	Description			
CMOS	Complementary Metal-Oxide Semiconductor			
DUT	Device Under Test			
ESD	ElectroStatic Discharge			
HBM	Human Body Model			
MIL	Military			
MM	Machine Model			

# 13. Revision history

#### Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes		
HEF4020B_Q100 v.3	20211207	Product data sheet	-	HEF4020B_Q100 v.2		
Modifications:	<u>Section 1</u> and <u>Section 2</u> updated.					
HEF4020B_Q100 v.2	20181018	Product data sheet	-	HEF4020B_Q100 v.1		
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> </ul>					
HEF4020B_Q100 v.1	20140604	Product data sheet	-	-		

# 14. Legal information

#### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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